



POD and Error Approximations

- **Proper Orthogonal Decomposition** is a model order reduction technique for PDEs
- Provides modes from simulation data and a projection is used on the modes to obtain the reduced order model (ROM)
- Optimal method to "compress" data
- Extension of singular value decomposition (SVD) for matrices
- POD depends on the Hilbert space structure of the data space
- The POD changes with the norm
- Errors of these models are of concern.
- Changing norms, i.e., the way to measure the error, can change errors of approximation

Basic Problem

Let w be the solution of the PDE and w_r be the solution of the ROM. The error is

 $w - w_r = (w - \pi_r w) + (\pi_r w - w_r),$

where π_r is a projection. How does $w - \pi_r w$

behave in the POD setting?

Background

- Linear operator $L: X \to Y$, where X and Y are Hilbert spaces
- Two sets of data: $\{w_k\} \subset X$ and $\{Lw_k\} \subset Y$
- POD operator $K: S \rightarrow X$ with SVD given by $Kf = \sum_{j=1}^{m} \sigma_j (f, f_j)_S \varphi_j$
- Two projections: $\Pi_r^X : X \to X$ is the orthogonal projection onto $span\{\varphi_k\}$ and $\Pi_r^Y: Y \to Y$ is a projection onto $span\{L\varphi_k\}$
- Known error for the data $\{w_j\} \subset X$:

 $\sum_{k=1}^{m} \left\| w_j - \Pi_r^X w_j \right\|_X^2 = \sum_{k>r} \sigma_k^2$

And

Note that *L* is unbounded and closed.

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Mathematics

Main Results

Theorem 1: If $\{w_k\}$ is in the domain of *L* and $\sigma_r > 0$, data approximation errors are given by

$$\sum_{j=1}^{m} \|Lw_j - L\Pi_r^X w_j\|_Y^2 = \sum_{k>r} \sigma_k^2 \|L\varphi_k\|_Y^2$$
$$\sum_{j=1}^{m} \|Lw_j - \Pi_r^Y Lw_j\|_Y^2 = \sum_{k>r} \sigma_k^2 \|L\varphi_k - \Pi_r^Y L\varphi_k\|_Y^2$$

$$\sum_{j=1}^{m} \left\| w_j - L^{-1} \Pi_r^{Y} L w_j \right\|_X^2 = \sum_{k>r} \sigma_k^2 \left\| \varphi_k - L^{-1} \Pi_r^{Y} L \varphi_k \right\|_X^2$$

Further, there are conditions which guarantee the convergence of these norms.

Theorem 2: Assume L is bounded and $\{\Pi_r^Y\}$ is uniformly bounded in operator norm. If $y \in \mathcal{R}(L)$, then $\Pi_r^Y y \to y$ as r increases.

In addition, if $\mathcal{R}(L)$ is dense in *Y*, then $\Pi_r^Y y \to y$ for all $y \in Y$.

Numerical Example

Consider a nerve impulse transmission model: the 1D FitzHugh-Nagumo system given by

$$\frac{\partial v(t,x)}{\partial t} = \mu \frac{\partial^2 v(t,x)}{\partial x^2} - \frac{1}{\mu} w(t,x) + \frac{1}{\mu} f(v) + \frac{c}{\mu},$$
$$\frac{\partial w(t,x)}{\partial t} = bv(t,x) - \gamma w(t,x) + c, \qquad 0 < x$$

where f(v) = v(v - 0.1)(1 - v), $\mu = 0.015$, b = 0.5, $\gamma = 2$, c = 0.05, the boundary conditions are $v_x(t, 0) = -50000t^3e^{-15t}$, $v_x(t, 1) = 0$, and the initial conditions are zero.

The Hilbert spaces are X = Y = $L^{2}(0,1) \times L^{2}(0,1)$ with the usual inner product.

Define the operator $L: X \to Y$ by (11) (2)

$$L\begin{pmatrix}\nu\\w\end{pmatrix} = \begin{pmatrix}\partial_x\nu\\\partial_xw\end{pmatrix}$$



Formula	Norm	Actual Error	Error Formula	Difference
$w_j - \Pi_r^X w_j$	Х	6.2755e-05	6.2792e-05	3.7584e-08
$Lw_j - L\Pi_r^X w_j$	Y	2.1584e-01	2.1593e-01	9.1863e-05
$Lw_j - \Pi_r^Y Lw_j$	Y	9.8536e-03	9.8541e-03	4.7712e-07

Table 1: Errors for r = 4

Formula	Norm	Actual Error	Error Formula	Difference
$w_j - \Pi_r^X w_j$	Х	4.145e-08	4.148e-08	3.366e-11
$Lw_j - L\Pi_r^X w_j$	Y	2.253e-04	2.254e-04	5.214e-08
$Lw_j - \Pi_r^{\mathrm{Y}} Lw_j$	Y	1.266e-05	1.266e-05	3.515e-09

Table 2: Errors for r = 12



 $||_{Y}$

 $\mathcal{O}_k \|_{\mathbf{Y}}$

0 < x < 1

< 1

More Results

- Main results can be extended to the case of continuous time data.
- Results hold for a non-orthogonal projection Π_r^Y , in particular we can use a Ritz projection.
- The generalized framework allows for consideration of spaces with semi-norms.
- Results include properties of various POD projections including pointwise convergence
- Before these results, inverse inequalities were used to bound the errors. Now we have exact error formulas that do not require inverse estimates.
- These results refine existing data approximation results and provide new extensions.

Future Research

- When are the projections involving the inverse of the operator uniformly bounded?
- Consider new ways of including difference quotients in POD ROMS with the goal to improve accuracy and efficiency Explore pointwise in time error bounds for POD ROMs

References

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John R. Singler. New POD Error Expressions, Error Bounds, and Asymptotic Results for Reduced Order Models of Parabolic PDEs. SIAM Journal on Numerical Analysis, vol. 52, no. 2, 2014, pp.852-876.

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