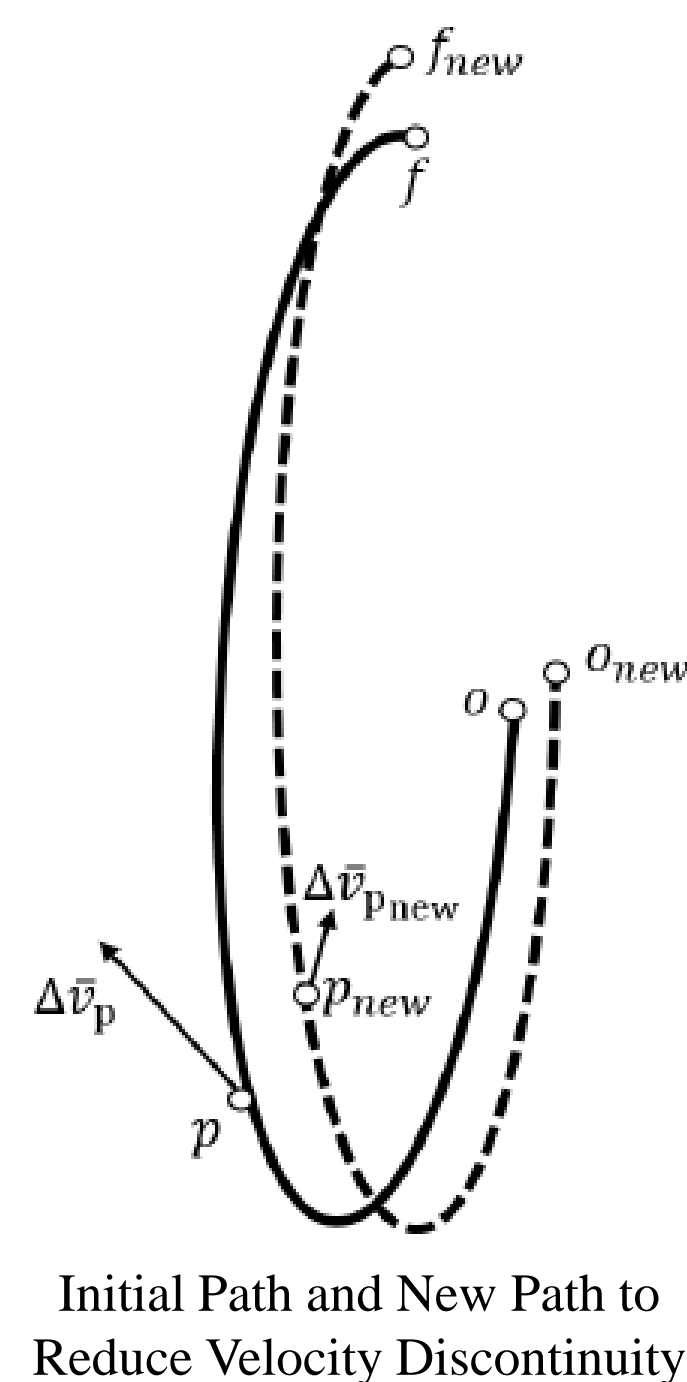


Background

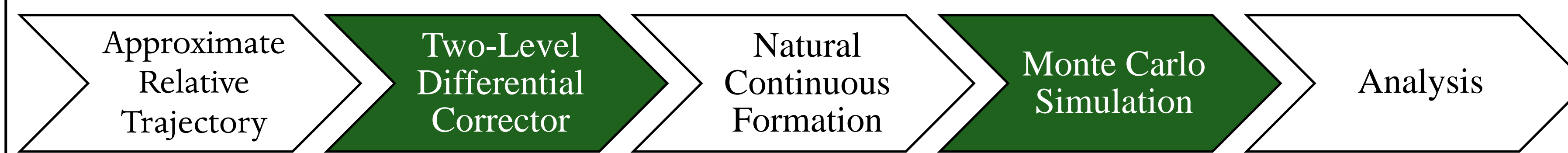
- Spacecraft formations allow for distributed spacecraft technologies, mission flexibility, and mission redundancy
- Thorough understanding of the relative dynamics is necessary to perform trajectory planning, meeting mission requirements, and collision avoidance
- Deep space applications include servicing monolithic spacecraft and providing a communication link for deep space assets
- Goal** – Identify natural relative trajectories at the L_1 and L_2 libration points

Two-Level Differential Corrector

- Initialize with patch points of desired trajectory
- Level 1 Differential Corrector: Iterative process to determine continuous path
- Level 2 Differential Corrector: Minimizes all velocity discontinuities



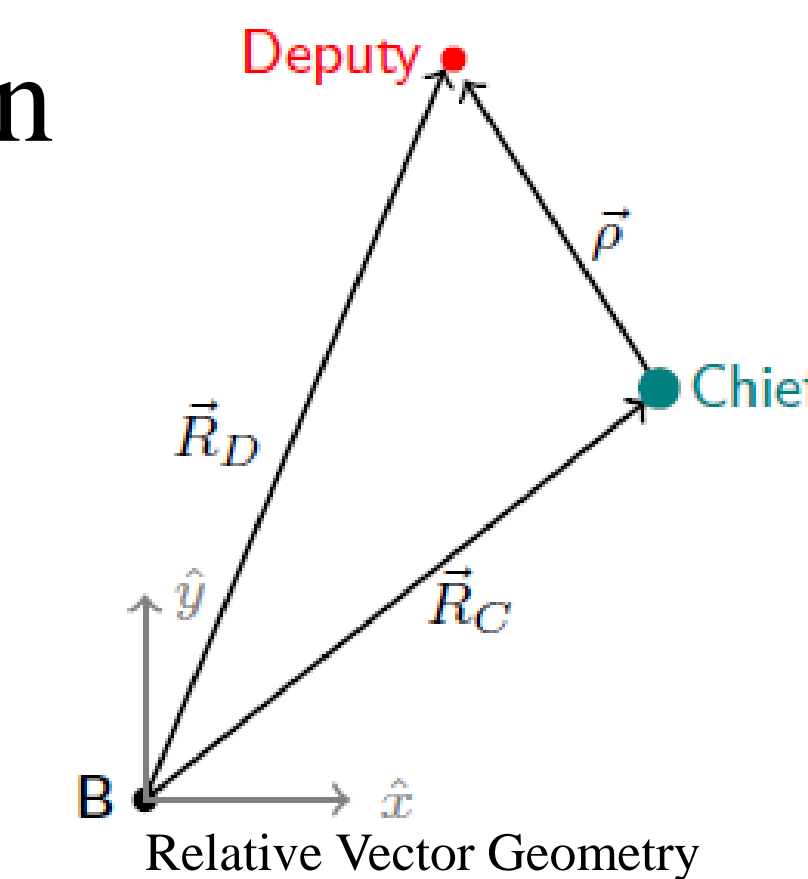
Method



- Utilized a linear approximation to initialize relative trajectory

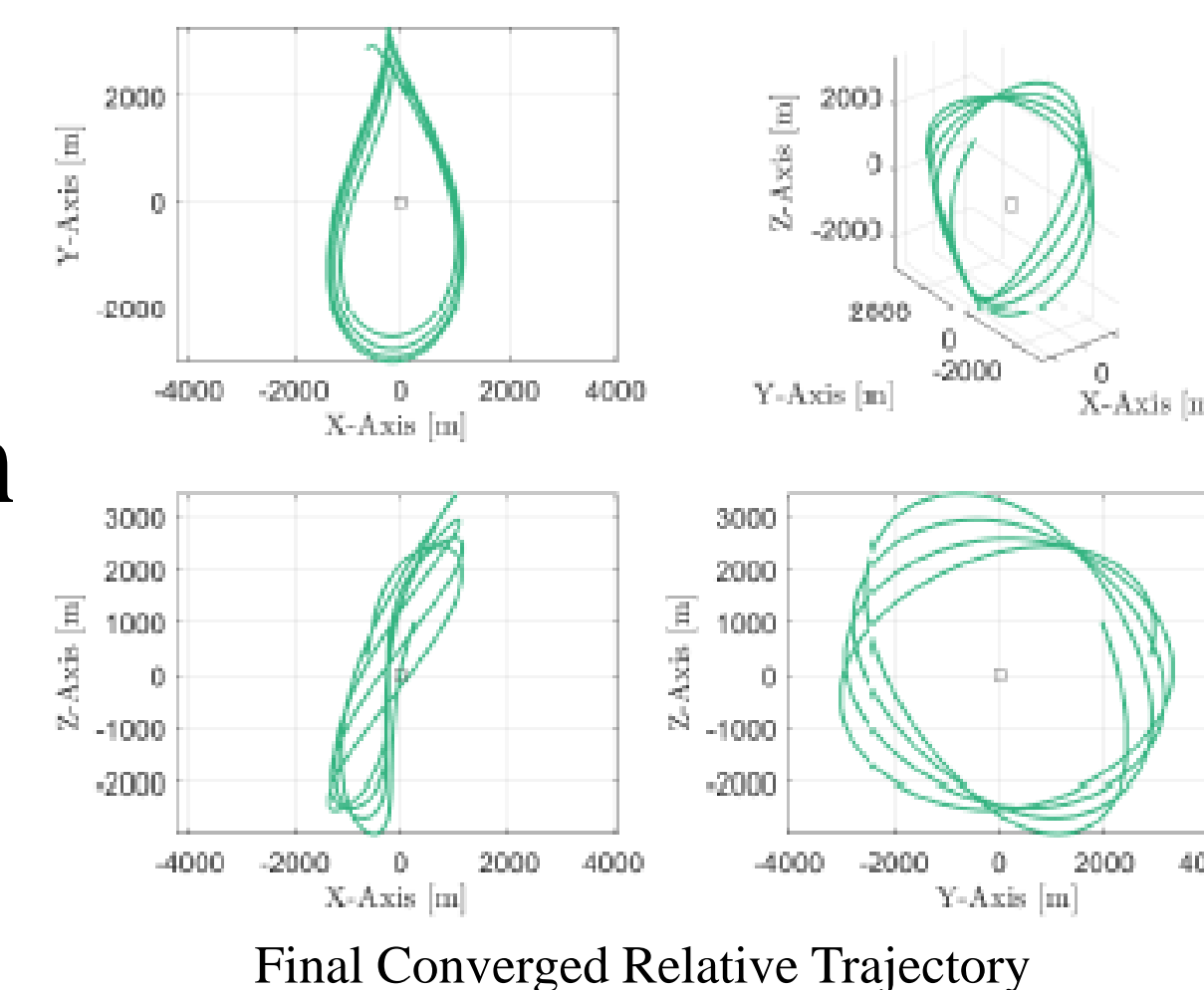
$$\begin{aligned}\rho_x &= -A_x \cos(\lambda t + \phi) \\ \rho_y &= kA_x \sin(\lambda t + \phi) \\ \rho_z &= A_z \sin(\nu t + \psi)\end{aligned}$$

- Implemented a shooting method with a two-level differential corrector to identify a natural continuous formation
- Performed Monte Carlo analysis:
 - Independent Variables: Injection error, relative navigation error, and actuator error
 - Dependent Variable: Amount of propellant needed to maintain formation flight



Results

- Desired relative position of 3 km
- Numerical trajectory converged after 33 iterations
- Patch points moved an average of 0.6 km and 0.004 km/s
- Monte Carlo simulation to determine stationkeeping costs
 - Linear quadratic regulator utilized for stationkeeping
 - 1,000 samples
 - Impulsive maneuvers



Final Converged Relative Trajectory

Stationkeeping Results of Monte Carlo Simulation

Trajectory Type	Mean ΔV [m/s]	Standard Deviation [m/s]
Numerical	0.475	0.027
Linear	1.802	0.412

Conclusions

- Demonstrated a numerical approach to finding natural relative formations in deep space
- Compared the numerical trajectory to the established linearized solution
 - Numerical trajectory has lower stationkeeping costs
 - Linearized solution drifts away from desired quicker than numerical trajectory

Future Work

- Incorporating higher fidelity dynamic models of spacecraft motion
- Investigating different control techniques and their effect on stationkeeping costs
- Identifying other natural and nonnatural formations possible in deep space
- Managing formation initialization and reconfiguration
- Accommodating thrust-limited propulsion systems

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